

Searches for User *gphilippe* (Count = 210)

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<u>S210</u>	<u>U</u>	USPT	(time near3 difference) and reproduc\$ and encod\$3 and predict\$3 and (continuous\$ near3 display\$3 with picture\$1) and (starting or beginning) and (terminating or ending)	2004-12- 28 17:26:43	
<u>S209</u>	<u>U</u>	USPT	reproduc\$ and encod\$3 and predict\$3 and (continuous\$ near3 display\$3 with picture\$1) and (starting or beginning) and (terminating or ending)	2004-12- 28 17:21:19	
<u>S208</u>	<u>U</u>	USPT	(continuous\$ near3 display\$3 with picture\$1) and (starting or beginning) and (terminating or ending)	2004-12- 28 17:20:33	
<u>S207</u>	<u>U</u>	USPT	(skipping or skipped or skip\$1) and (start\$3 and ending or end or ended) and predictive and (encod\$3 and decod\$3) and ((continuous\$ with display\$ with picture\$1) and (time difference or time lapse\$1 or differenc\$3) and (reproduction or reproducing or reproduced))	2004-12- 28 16:07:43	
<u>S206</u>	<u>U</u>	USPT	(start\$3 and ending or end or ended) and predictive and (encod\$3 and decod\$3) and ((continuous\$ with display\$ with picture\$1) and (time difference or time lapse\$1 or differenc\$3) and (reproduction or reproducing or reproduced))	2004-12- 28 16:07:04	
<u>S205</u>	<u>U</u>	USPT	predictive and (encod\$3 and decod\$3) and ((continuous\$ with display\$ with picture\$1) and	2004-12- 28 16:06:34	

			(time difference or time lapse\$1 or differenc\$3) and (reproduction or reproducing or reproduced))	
<u>S204</u>	<u>U</u>	USPT	(encod\$3 and decod\$3) and	2004-12-
			((continuous\$ with display\$ with picture\$1) and (time difference or time lapse\$1 or differenc\$3) and (reproduction or reproducing or reproduced))	28 16:06:17
<u>S203</u>	<u>U</u>	USPT	((continuous\$ with display\$ with picture\$1) and (time difference or time lapse\$1 or differenc\$3) and (reproduction or reproducing or reproduced))	2004-12- 28 16:05:35
<u>S202</u>	<u>U</u>	USPT	(predict\$3 same frame sequence\$1) and frame differenc\$3 and (bidirection\$4 with predict\$3)	2004-12- 23 18:09:14
<u>S201</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	((quantization same matrix same ratio\$1) and (transcod\$3 or reencod\$3 or reencod\$3))	2004-12- 23 16:41:30
<u>S200</u>	<u>U</u>	USPT	6218960.pn.	2004-12- 23 13:07:04
<u>S199</u>	<u>U</u>	USPT	6218960.pn.	2004-12- 23 13:06:24
<u>S198</u>	<u>U</u>	USPT	5931253.pn.	2004-12- 23 13:06:15
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<u>S196</u>	<u>U</u>	USPT	5742141.pn.	2004-12- 23 13:05:26
<u>S195</u>	<u>U</u>	USPT	5742141.pn.	2004-12- 23 13:03:48
<u>S194</u>	<u>U</u>	USPT	steer\$ and camera\$1 and (size same vehicle\$1 same park\$3)	2004-12- 23 12:50:49
<u>S193</u>	<u>U</u>	USPT	camera\$1 and (size same vehicle\$1 same park\$3)	2004-12- 23 12:50:36
<u>S192</u>	<u>U</u>	USPT	(size same vehicle\$1 same park\$3)	2004-12- 23 12:50:09

<u>S191</u>	<u>U</u>	USPT	6654670	2004-12-23 12:48:44
<u>S190</u>	<u>U</u>	USPT	(refin\$3 with motion same grid\$1 same mode vector\$ point\$1)	2004-12-23 12:45:56
<u>S189</u>	<u>U</u>	USPT	motion vector\$1 and grid\$1 and mode\$1 and (linear with function same match\$3 with error\$1) and points	2004-12-23 12:36:13
<u>S188</u>	<u>U</u>	USPT	grid\$1 and mode\$1 and (linear with function same match\$3 with error\$1) and points	2004-12-23 12:35:23
<u>S187</u>	<u>U</u>	USPT	mode\$1 and (linear with function same match\$3 with error\$1) and points	2004-12-23 12:35:08
<u>S186</u>	<u>U</u>	USPT	(linear with function same match\$3 with error\$1) and points	2004-12-23 12:34:42
<u>S185</u>	<u>U</u>	USPT	linear\$ and (matching with error same motion vector predict\$)	2004-12-23 12:32:13
<u>S184</u>	<u>U</u>	USPT	(matching with error same motion vector predict\$)	2004-12-23 12:29:56
<u>S183</u>	<u>U</u>	USPT	(6724823 or 6829373 or 6480543 or 6456659).pn.	2004-12-23 12:05:35
<u>S182</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	filter\$3 and (motion same image sequence\$1) and (segment\$3 with motion vector field)	2004-12-22 20:20:05
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<u>S179</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	((disparit\$ with map\$1) same filter\$3) and (segment\$3 with motion vector field)	2004-12-22 20:18:57
<u>S178</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(velocity same region\$1 same filter\$3) and (motion with vector with field) and (map\$3 with compar\$)	2004-12-22 20:13:10
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<u>S175</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(optical with unit\$1 with detect\$3 same sens\$3)	2004-12-22
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			16:52:40
<u>S173</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(switch\$ same stereoscop\$) and ((detect\$ same (stereoscop\$ or three-dimension\$ or 3-D or 3D)) same (sensing or sensed or senses))	2004-12-22
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<u>S172</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(((detect\$ same (stereoscop\$ or three-dimension\$ or 3-D or 3D)) same (sensing or sensed or senses))	2004-12-22
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<u>S170</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(motion with predict\$) and 5988863.pn.	2004-12-22
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<u>S169</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPIpredict\$ and 5988863.pn.	2004-12-22
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<u>S166</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPIvector and 5796439.pn.	2004-12-22
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<u>S164</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(resolution with conver\$ same frame rate with conver\$) and encod\$3	2004-12-22
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<u>S163</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI(frame near3 rate\$1) and 6584154.pn.	2004-12-22
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